

# AnyAnomaly: Zero-Shot Customizable Video Anomaly Detection with LVLM

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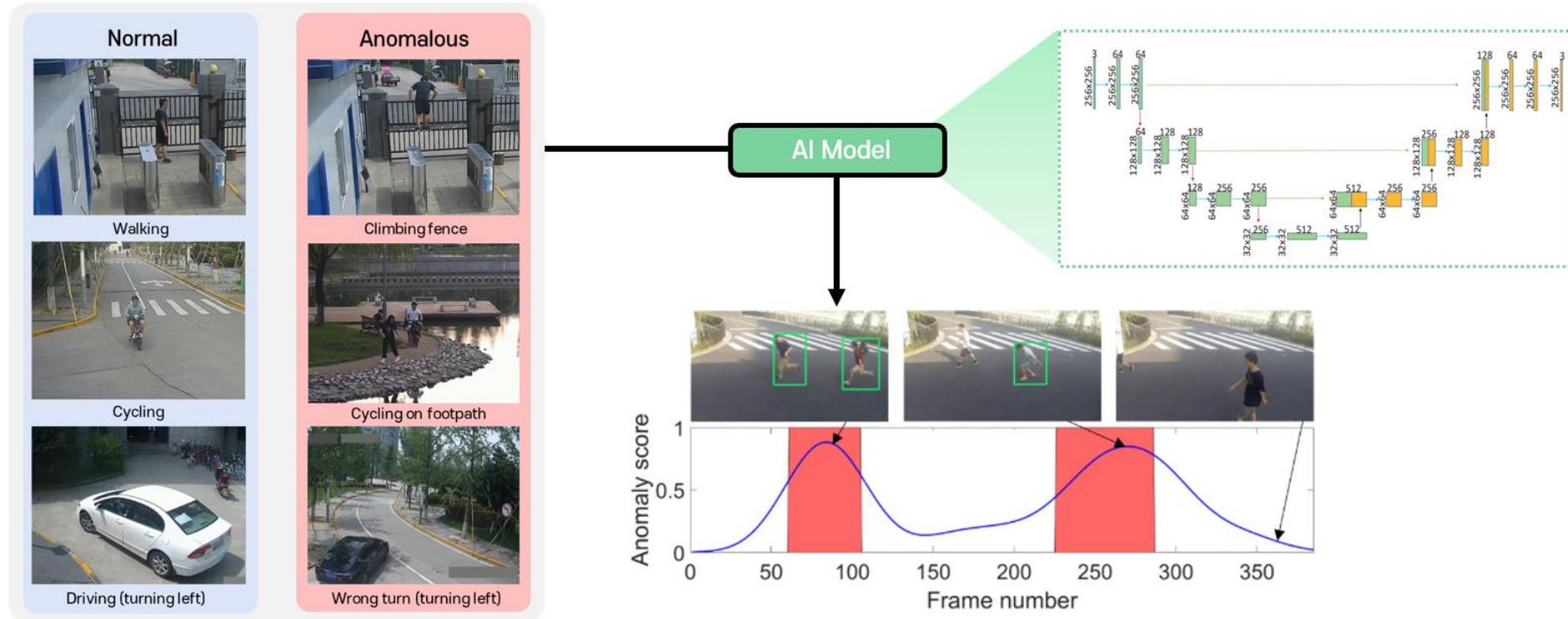
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\* Equal contribution  
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## Background

# Video Anomaly Detection

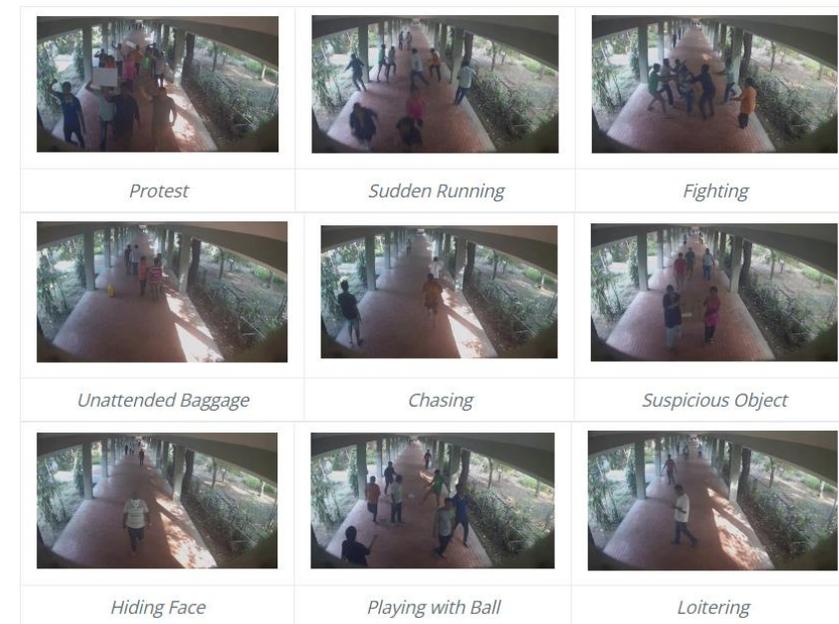
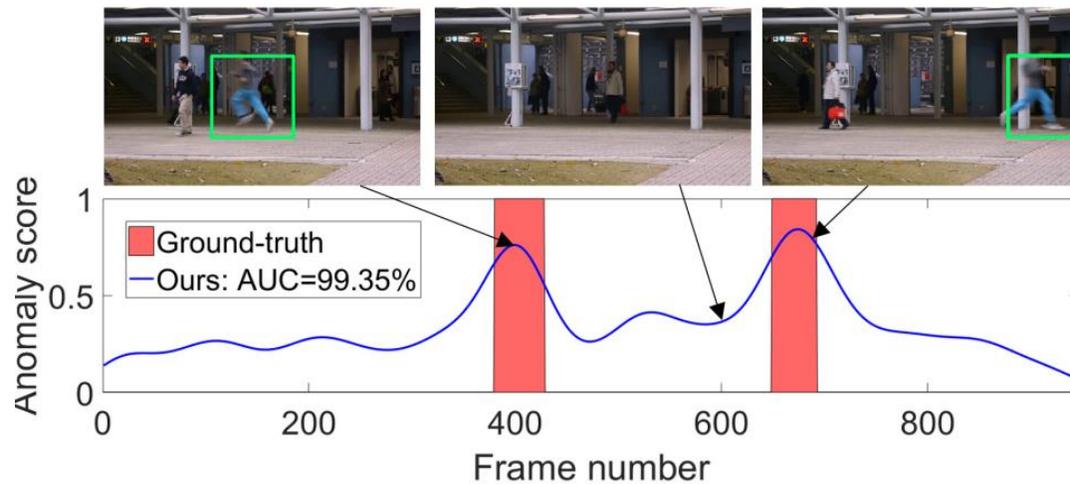
- Video Anomaly Detection (VAD) aims to determine whether abnormal events occur within video streams
- Abnormal events include the appearance or action of objects that are not suitable for the situation
- The goal is to do **Binary Classification** on each frame



## Background

# One Class Classification

- Class imbalance problem  $|\{x_i | y_i=0\}| \gg |\{x_i | y_i=1\}|$
- Diverse anomaly
- **One-Class Classification (OCC)** is utilized that learns exclusively from normal data and classifies anything not resembling the patterns of normal data as abnormal

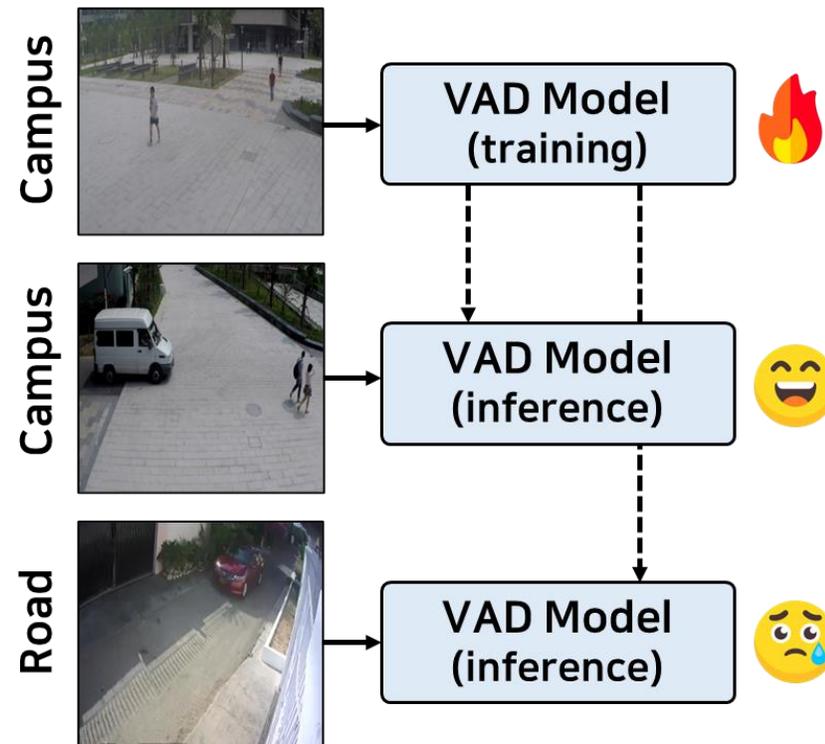


Rodrigues, Royston, et al. "Multi-timescale trajectory prediction for abnormal human activity detection." *Proceedings of the IEEE/CVF winter conference on applications of computer vision*. 2020.

## Introduction

# Problem Definition

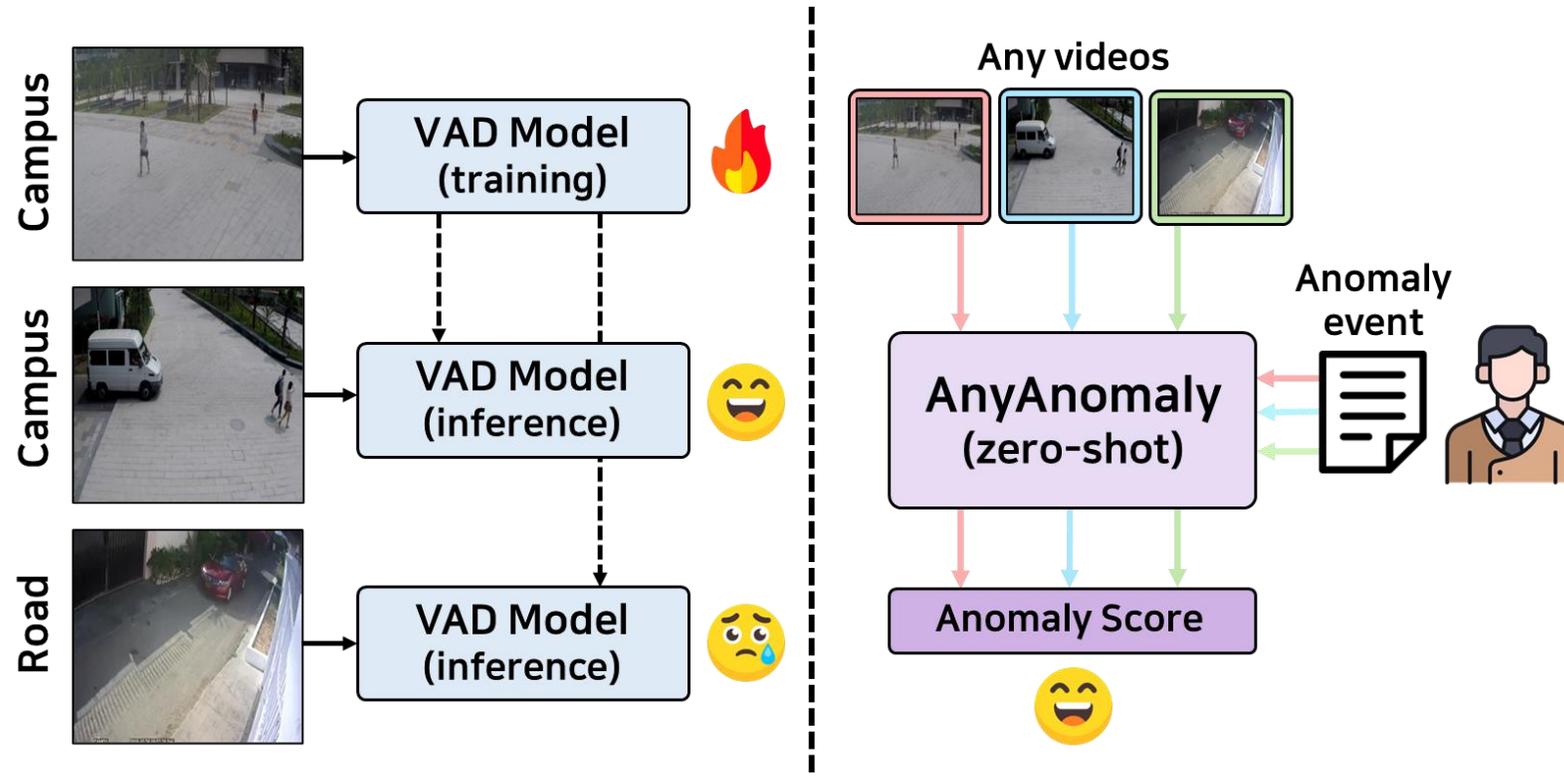
- VAD models learn normal patterns under specific scenarios, limiting **generalization to diverse environments**
- Models trained on pedestrian zones classify vehicles as anomalies, making deployment in road scenes difficult
- Adapting to new scenarios requires additional training or building separate models  
→ **increased computational cost and data collection**



# Introduction

## Key Idea

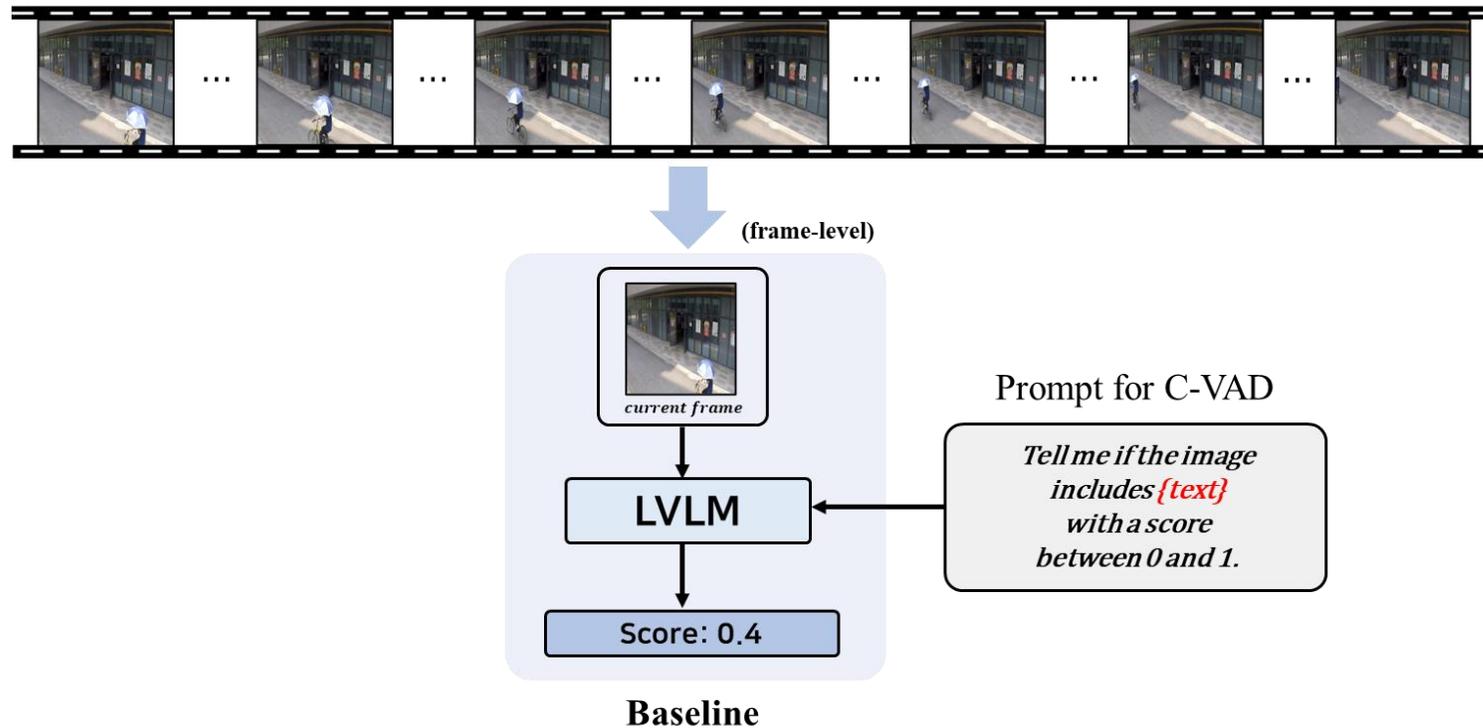
- Customizable Video Anomaly Detection (C-VAD): a zero-shot, text-driven VAD technique
- User-defined text descriptions specify abnormal events; frames containing the described events are detected
- No scenario-specific retraining or separate models are required



# Introduction

## Baseline

- Perform **frame-level VQA** using an **LVLM** to estimate an anomaly score
- Prompt the model to return a value between 0 (no) and 1 (yes), indicating the degree to which the input image contains the user-defined abnormal event
- However, this approach may suffer from several limitations

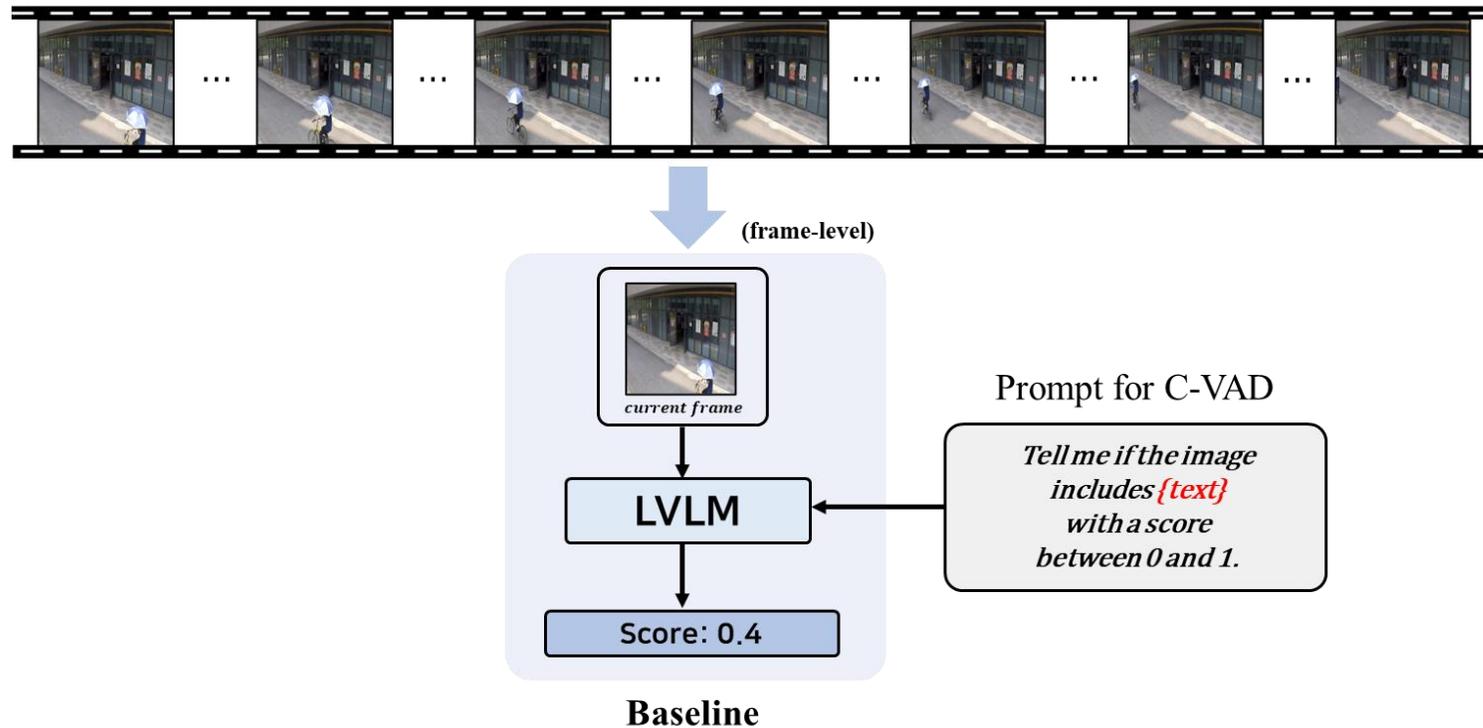


- VQA: Visual Question Answering
- LVLM: Large Vision Language Model

## Introduction

# Limitations of Baseline

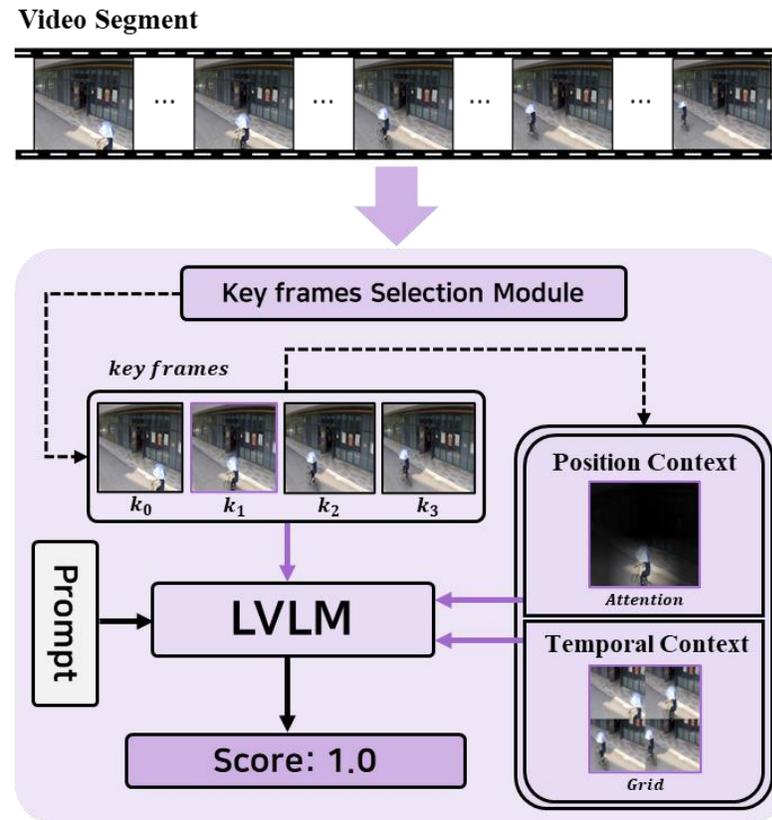
- As the number of frames increases, **inference latency grows significantly**
- Due to the characteristics of CCTV footage (foreground-background imbalance, object congestion), **accurate object-level analysis can be challenging**
- Processing images independently **limits temporal reasoning and makes behavior analysis difficult**



## Introduction

# AnyAnomaly

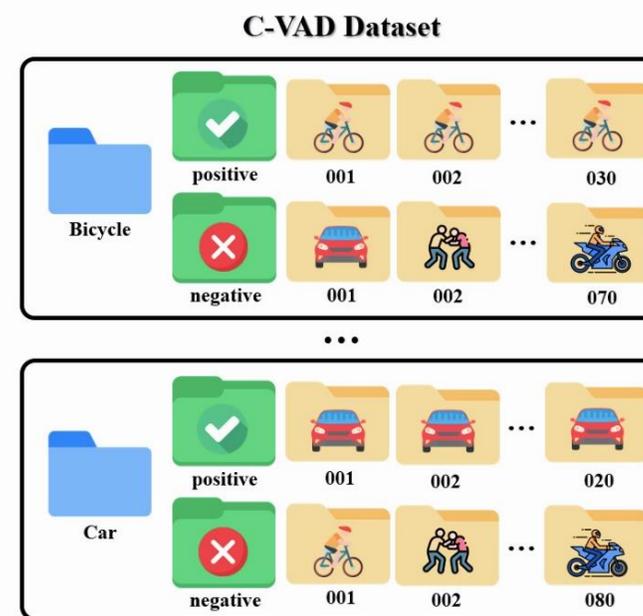
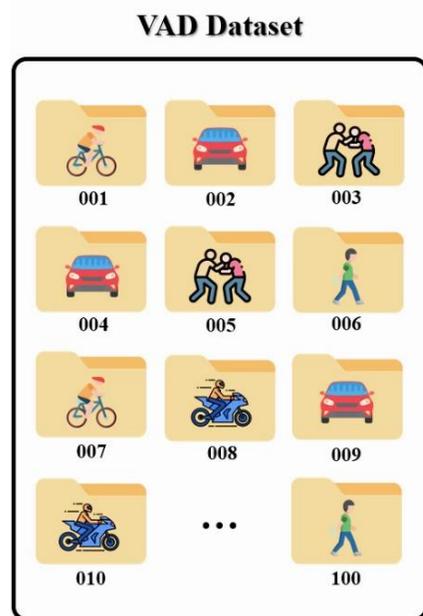
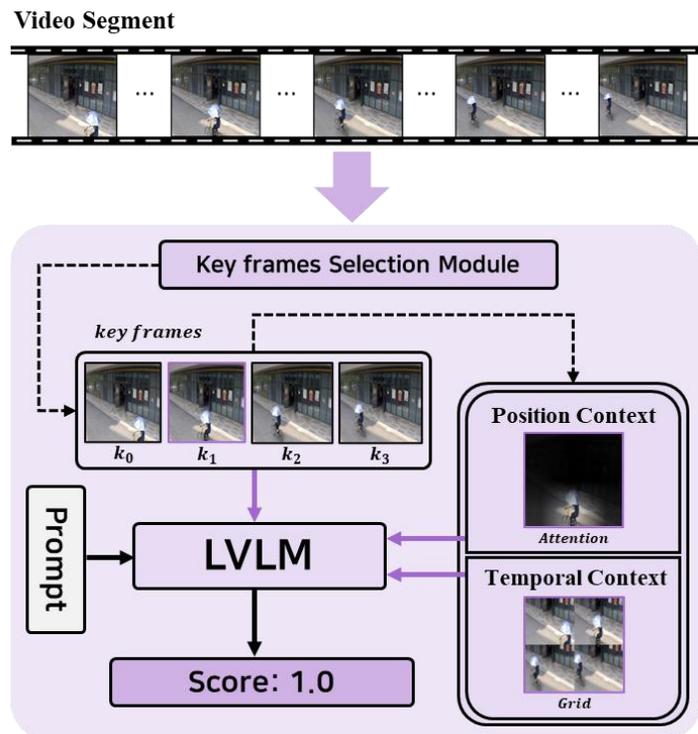
- **Segment-level approach:** select key frames and perform VQA per segment
- **Context-aware VQA:** perform VQA using additional contexts that represent the image
- **Position Context** emphasizes important spatial regions, while **Temporal Context** represents scene changes over time



# Introduction

## Contributions

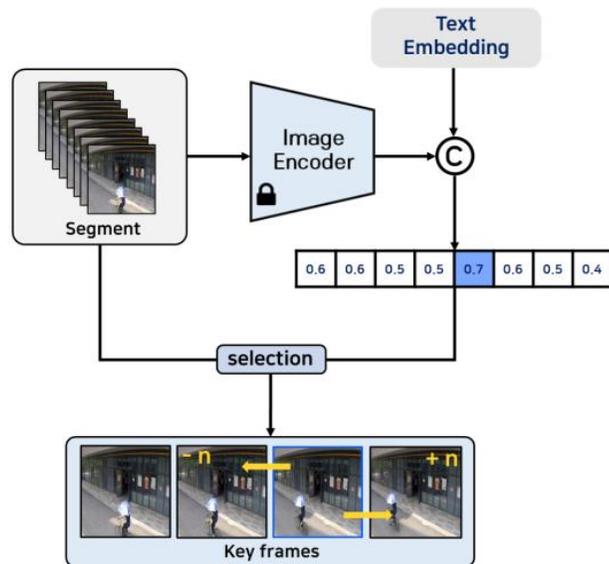
- Propose **C-VAD** for anomaly detection across diverse environments
- Develop **AnyAnomaly**, a context-aware VQA model for C-VAD
- Construct **C-VAD datasets** for rigorous evaluation and validate the effectiveness of the proposed method



# Method Architecture

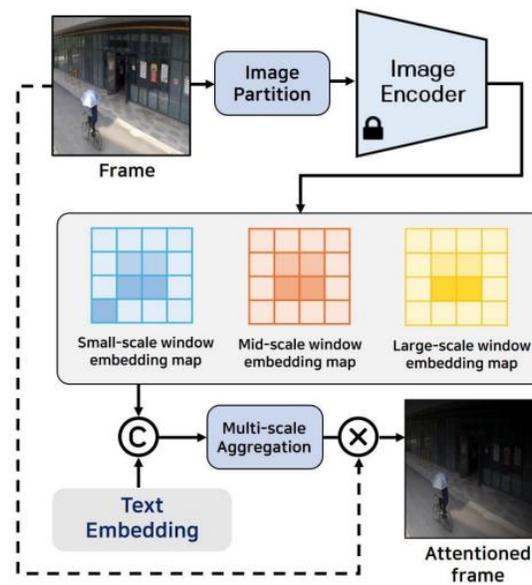
- **KSM**: method for segment-level approach (*reduces inference time*)
- **WA**: method for generating position context (*improves object-level analysis*)
- **GIG**: method for generating temporal context (*enhances behavior analysis*)

## Segment-level approach



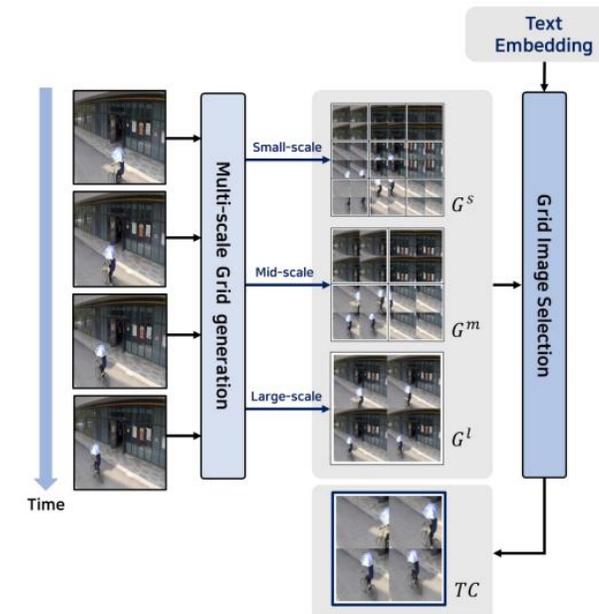
(a) Key frames Selection Module (KSM)

## Position Context



(b) WinCLIP-based Attention (WA)

## Temporal Context

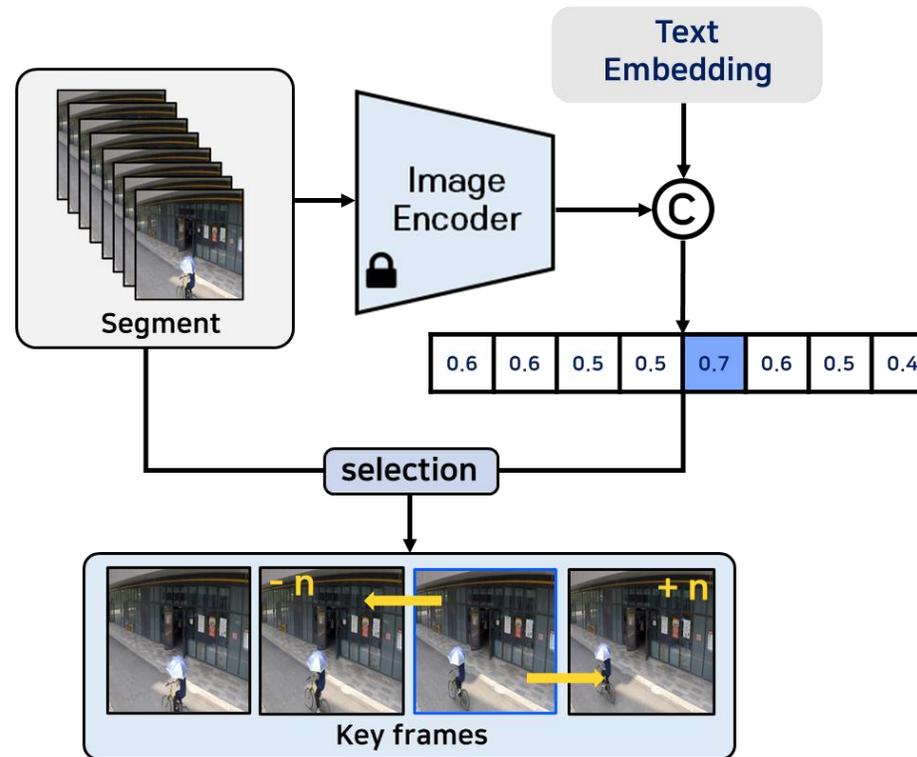


(c) Grid Image Generation (GIG)

## Method

# Key frames Selection Module

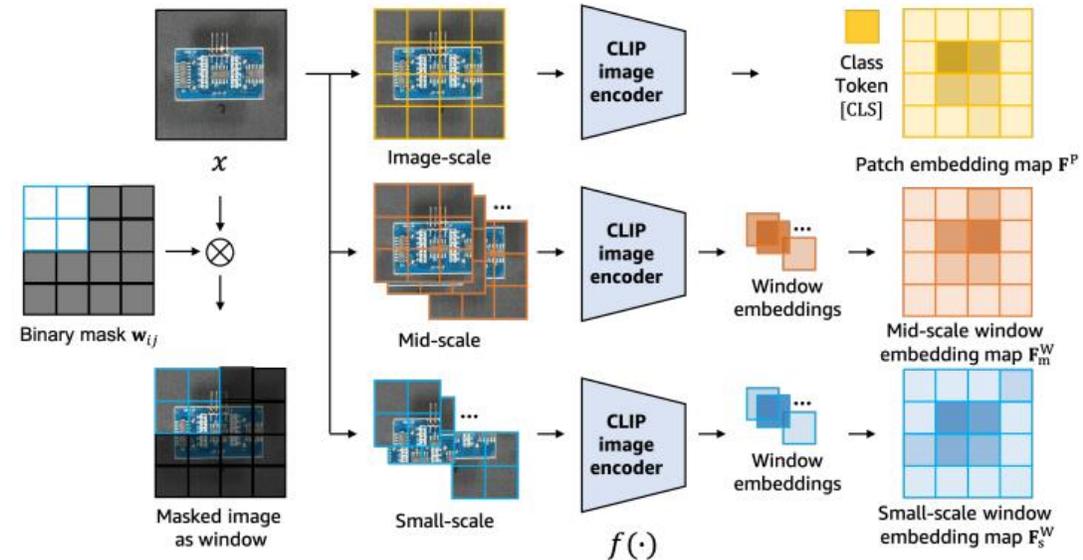
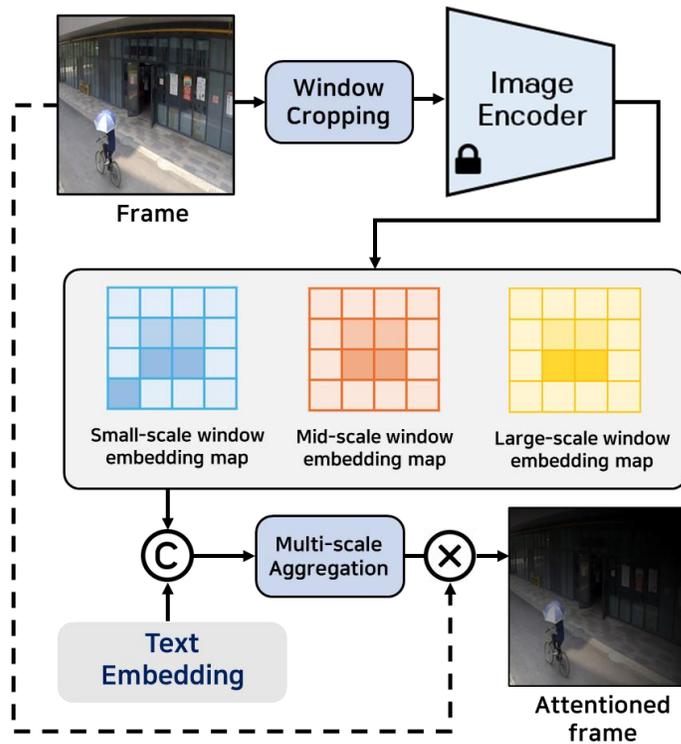
- Temporal uniformity and text alignment are critical in key frames extraction
- Use an image encoder (e.g., CLIP) to select frame most similar to the text embedding
- Divide the segment into multiple groups and select remaining frames based on the positions of the selected frame



## Method

# WinCLIP-based Attention

- Based on the window embedding maps proposed in WinCLIP, identify regions corresponding to the text
- Multi-scale embedding maps provide representations at both local and global scales
- The similarity map is obtained by averaging similarities across multiple scales and then used to reweight the input image

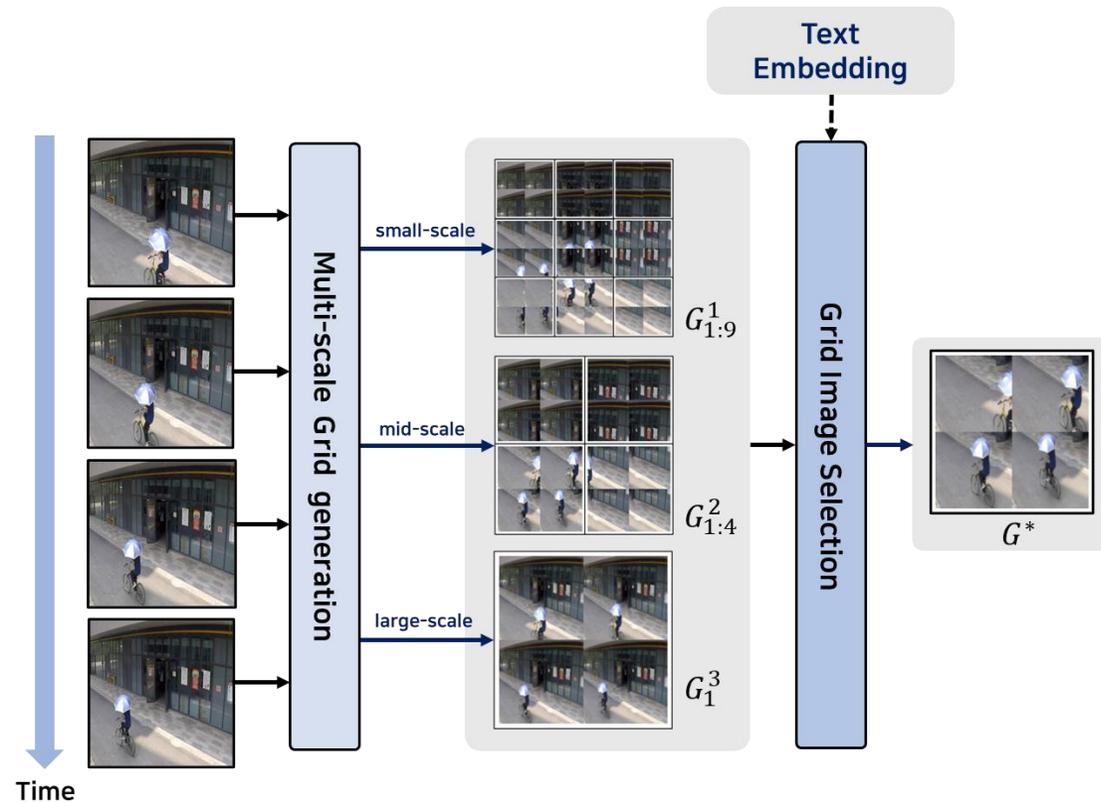


Jeong, J et al., "WinCLIP: Zero-/Few-Shot Anomaly Classification and Segmentation", Proceedings of the IEEE conference on computer vision and pattern recognition, pp.19606-19616, 2023.

## Method

# Grid Image Generation

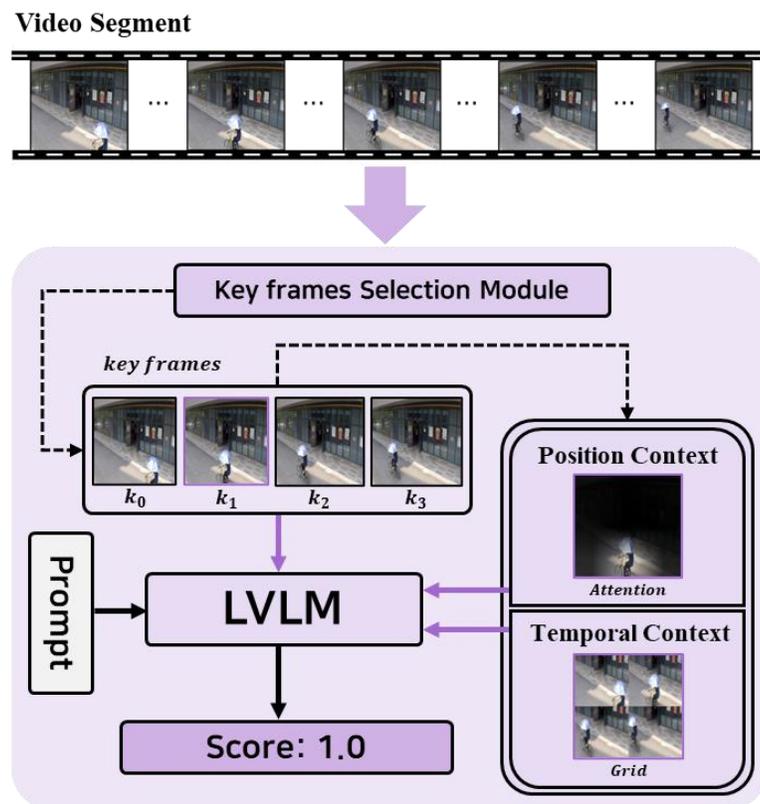
- Following the same procedure as WA, windows at the same spatial position across key frames are grouped at each scale
- The grouped windows are arranged into a 2×2 grid to form a grid image
- The grid image most relevant to the text embedding is selected



## Method

# Anomaly Scoring

- LVLM evaluates the representative key frame  $\hat{k}$  and position context  $PC$  using the shared prompt  $P$
- Temporal context  $TC$  is evaluated with a modified prompt  $P^*$
- The outputs are aggregated to compute the final anomaly score via late fusion



Detailed prompt

**Task:** Evaluate whether the given image includes **{text}** on a scale from 0 to 1. A score of 1 means **{text}** is clearly present in the image, while a score of 0 means **{text}** is not present at all. For intermediate cases, assign a value between 0 and 1 based on the degree to which **{text}** is visible.

**Consideration:** The key is whether **{text}** is present in the image, not its focus. Thus, if **{text}** is present, even if it is not the main focus, assign a higher score like 1.0.

**Output:** Provide the score as a float, rounded to one decimal place, including a brief reason for the score in one short sentence.

### Prompt for temporal context

**Context:** The given image represents a sequence (row 1 column 1 → row 1 column 2 → row 2 column 1 → row 2 column 2) illustrating temporal progression.

$$ascore = \gamma_1 \cdot \Phi_{LVLM}(\hat{k}, P) + \gamma_2 \cdot \Phi_{LVLM}(PC, P) + \gamma_3 \cdot \Phi_{LVLM}(TC, P^*)$$

## Results

# Main Results

- In existing VAD datasets, videos are not categorized by anomaly classes
- The proposed C-VAD datasets categorize videos by anomaly classes
- Each class contains positive and negative samples for evaluating user-specified anomaly detection

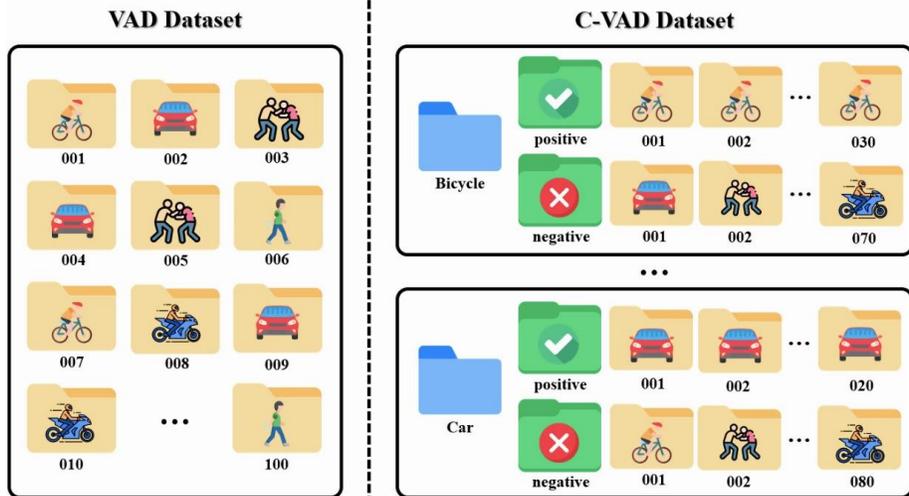


Table 1. Performance comparison on C-ShT dataset. The best results are **bolded**. The second-best results are underlined.

Category	Class	Baseline	+KSM	+KSM/PC	+KSM/TC	Proposed	Improvement (%)
Action	Skateboarding	<u>61.30</u>	57.06	57.79	<b>73.66</b>	<b>73.66</b>	+20.16
	Throwing	<b>91.41</b>	72.82	88.74	82.53	<u>90.67</u>	-0.81
	Running	53.13	51.93	53.68	<u>59.77</u>	<b>60.11</b>	+13.14
	Loitering	61.98	51.96	<b>81.27</b>	<u>76.94</u>	<b>81.27</b>	+31.12
	Jumping	82.84	92.89	<u>92.91</u>	<b>95.31</b>	<b>95.31</b>	+15.05
	Falling	78.31	78.95	79.24	<b>88.01</b>	<b>88.01</b>	+12.39
	Fighting	84.48	<u>91.18</u>	<u>91.18</u>	<b>98.06</b>	<b>98.06</b>	+16.07
	<b>Average</b>	73.35	72.00	77.83	<u>82.04</u>	<b>83.87</b>	+14.34
Appearance	Car	88.72	<u>90.96</u>	<b>91.46</b>	<u>90.96</u>	<b>91.46</b>	+3.09
	Hand truck	95.50	<u>98.20</u>	<u>98.91</u>	<b>99.20</b>	<b>99.20</b>	+3.87
	Bicycle	72.36	<u>72.46</u>	<b>78.47</b>	<u>72.46</u>	<b>78.47</b>	+8.44
	Motorcycle	<b>88.04</b>	<u>86.72</u>	<u>86.72</u>	<u>86.72</u>	<u>86.72</u>	-1.50
	<b>Average</b>	86.16	87.09	<u>88.89</u>	87.34	<b>88.95</b>	+3.25
<b>Overall Average</b>		78.01	77.48	81.85	<u>83.97</u>	<b>85.72</b>	+9.88

Table 2. Performance comparison on C-Ave dataset

Category	Class	Baseline	+KSM	+KSM/PC	+KSM/TC	Proposed	Improvement (%)
Action	Throwing	78.44	80.13	<b>89.77</b>	<u>82.40</u>	<b>89.77</b>	+14.44
	Running	75.82	<u>77.67</u>	<u>77.67</u>	<b>77.90</b>	<b>77.90</b>	+2.74
	Dancing	<u>85.65</u>	72.28	76.64	<b>91.92</b>	<b>91.92</b>	+7.32
	<b>Average</b>	79.97	76.69	81.36	<u>84.07</u>	<b>86.53</b>	+8.2
Appearance	Too close	57.23	<u>61.48</u>	<u>61.48</u>	<b>91.78</b>	<b>91.78</b>	+60.37
	Bicycle	<u>99.99</u>	99.84	<u>99.99</u>	99.93	<b>100.00</b>	+0.01
	<b>Average</b>	78.61	80.66	80.74	<u>95.86</u>	<b>95.89</b>	+21.98
<b>Overall Average</b>		79.43	78.28	81.11	<u>88.79</u>	<b>90.27</b>	+13.65

## Results

# Ablation Study

Table S2. Comparison on segment length

Segment length	C-ShT	C-Ave	FPS
Baseline	78.01	79.43	0.96
8	83.83	83.96	2.67
16	83.45	87.45	4.49
24	<b>85.72</b>	<b>90.27</b>	6.67
32	82.50	85.94	<b>8.45</b>

Table 4. Comparison on window size.

Window Size	C-ShT			C-Ave		
	Act.	App.	Total	Act.	App.	Total
small	78.8	<b>90.6</b>	83.1	84.7	87.1	85.7
middle	81.2	89.0	84.1	<b>87.5</b>	92.0	89.3
large	82.1	89.7	84.9	86.8	86.4	86.6
all	<b>83.9</b>	89.0	<b>85.7</b>	86.5	<b>95.9</b>	<b>90.3</b>

Table S4. Comparison of diverse LVLMs. The model highlighted in blue represents the most efficient model for the C-VAD task, while the one highlighted in purple indicates the most effective model. For further comparison, additional experiments were conducted using Qwen-based models. \*: Experiment conducted using vLLM.

LVLM	Pre-trained	C-ShT		C-Ave		FPS
		w/o context	Proposed	w/o context	Proposed	
Chat-UniVi[14]	Chat-UniVi-7B	77.5	<u>85.7</u>	78.3	<u>90.3</u>	6.67
MiniGPT-4[44]	LLaMA-2 Chat 7B	54.0	67.4	53.9	55.3	1.26
MiniCPM-V[41]	MiniCPM-Llama3-V-2.5 (8B)	87.7	<b>90.1</b>	86.3	<b>91.0</b>	1.36
LLAVA++[28]	LLaVA-Meta-Llama-3-8B-Instruct-FT	73.3	82.8	59.0	69.4	7.25
Qwen2.5-VL[6]	Qwen2.5-VL-3B-Instruct	89.0	<u>90.2</u>	78.0	87.0	11.18
Qwen2.5-VL*[6]	Qwen2.5-VL-3B-Instruct	88.6	<u>90.2</u>	78.3	<u>88.1</u>	34.78
Qwen2.5-VL*[6]	Qwen2.5-VL-7B-Instruct	93.0	<b>95.5</b>	86.9	<b>92.4</b>	24.08

## Results

# Performance Comparison

Table 5. Comparison with state-of-the-art VAD methods. \* indicates testing without context.

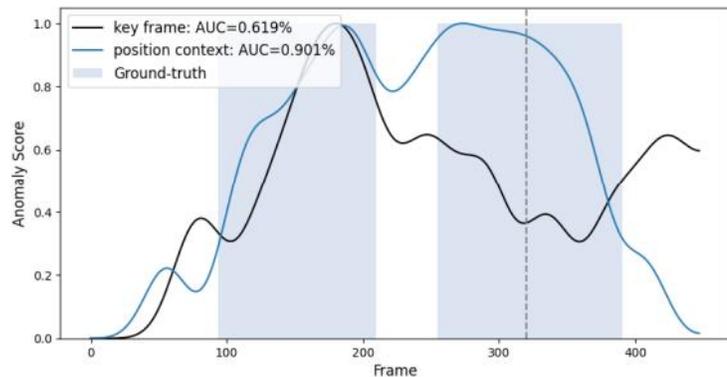
Method	Zero-shot	Ave	ShT	UB	UCF
AMMC-Net[7]	✗	86.6	73.7	-	-
STEAL-Net[5]	✗	87.1	73.7	-	-
MPN[23]	✗	89.5	73.8	-	-
DLAN-AC[39]	✗	89.9	74.7	-	-
UBnormal[1]	✗	-	-	68.5	-
FPDM[37]	✗	90.1	78.6	62.7	74.7
SLM[33]	✗	<u>90.9</u>	78.8	-	-
USTN-DSC[40]	✗	89.9	73.8	-	-
AnomalyRuler[38]	✗	89.7	<b>85.2</b>	71.9	-
MULDE[26]	✗	-	<u>81.3</u>	72.8	<u>78.5</u>
AED-MAE[30]	✗	<b>91.3</b>	79.1	58.5	-
MA-PDM[43]	✗	<b>91.3</b>	79.2	63.4	-
AccI-VAD[29]	✗	-	76.2	66.8	60.3
AnyAnomaly*	✓	81.4	77.2	<u>73.1</u>	77.8
AnyAnomaly	✓	87.3	79.7	<b>74.5</b>	<b>80.7</b>

Table 6. Generalization performance comparison. Tr.: cross-domain training where models trained on one VAD dataset are evaluated on another. Few.: methods that adapt to the target domain using only a few training samples, Aux.: methods that utilize auxiliary datasets, \*: since competitors did not perform cross-domain evaluations on ShT, we present their same-domain results instead.

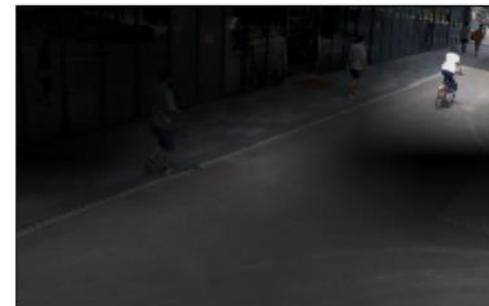
Method	Tr.	Few.	Aux.	Ave	ShT
STEAL-Net[5]	✓	✗	✗	54.3	51.7
Jigsaw[35]	✓	✗	✗	62.9	59.3
rGAN[21]	✓	✓	✗	76.6	77.9*
MPN[23]	✓	✓	✗	78.9	73.8*
zxVAD[3]	✓	✗	✓	82.2	71.6*
Shibao et al.[9]	✓	✗	✓	<u>86.2</u>	<u>78.7</u>
ZS CLIP[27]	✗	✗	✗	62.3	60.9
ZS ImageBind[10]	✗	✗	✗	64.5	61.3
LLaVA-1.5[18]	✗	✗	✗	67.4	59.6
Video-ChatGPT[24]	✗	✗	✗	76.9	69.1
AnyAnomaly	✗	✗	✗	<b>87.3</b>	<b>79.7</b>

## Results

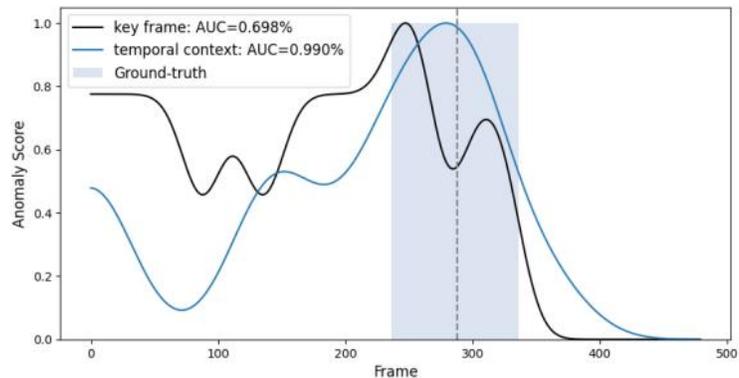
# Qualitative Results



The image does not show a clear **bicycle**, so the score is **0.4**.



The image includes a group of people riding **bicycles**, with at least one clearly visible bicycle. The score would be **0.9**.



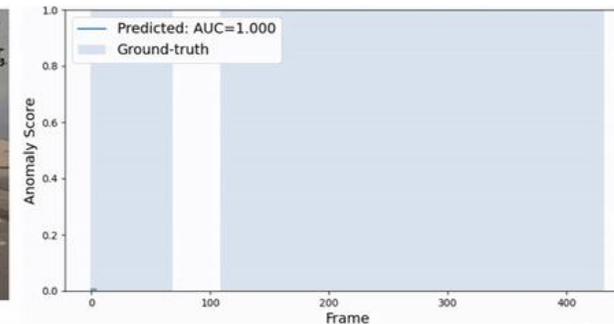
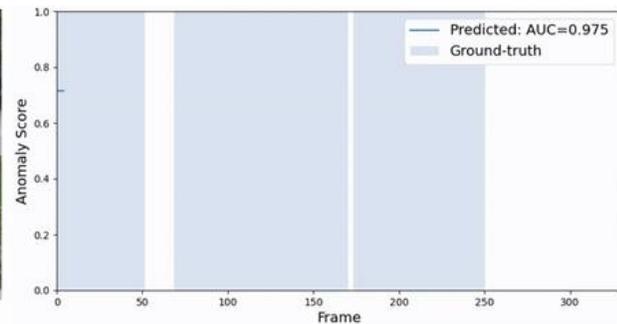
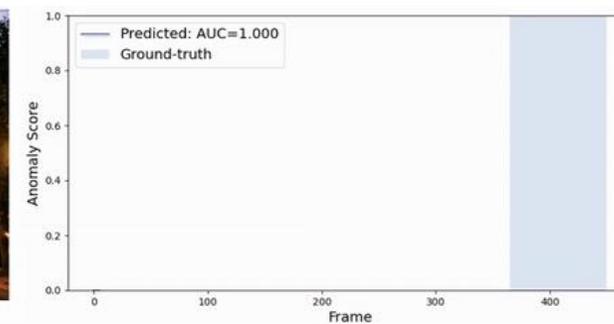
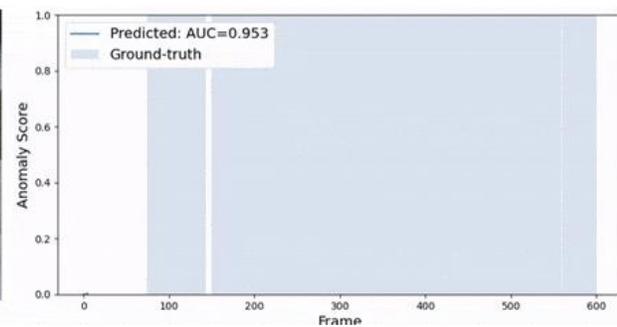
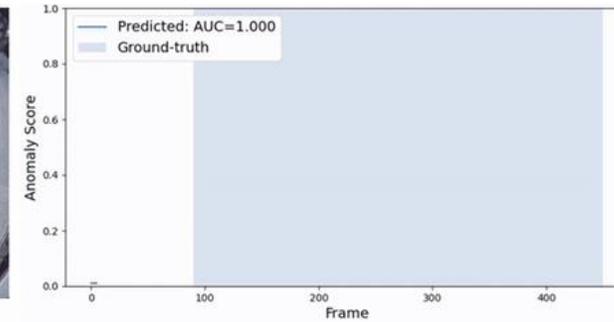
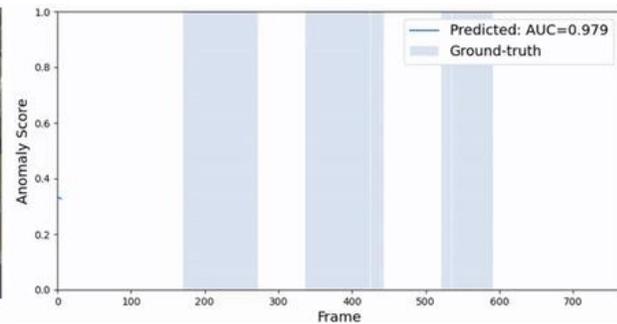
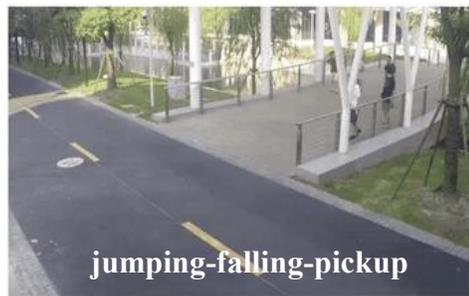
The image shows a group of young men standing on a paved area, but there is no evidence of **fighting**. The score is **0.5**.



The image shows a group of people **fighting**, with at least two individuals engaged in physical altercations. The score is **0.9**.

# Results

## Demos



**Thank you**